# CURVATURE-TORSION ENTROPY FOR TWISTED CURVES UNDER CURVE SHORTENING FLOW 

GABRIEL KHAN

(Received 16 May 2023; accepted 25 May 2023; first published online 11 July 2023)


#### Abstract

We study curve-shortening flow for twisted curves in $\mathbb{R}^{3}$ (that is, curves with nowhere vanishing curvature $\kappa$ and torsion $\tau$ ) and define a notion of torsion-curvature entropy. Using this functional, we show that either the curve develops an inflection point or the eventual singularity is highly irregular (and likely impossible). In particular, it must be a Type-II singularity which admits sequences along which $\tau / \kappa^{2} \rightarrow \infty$. This contrasts strongly with Altschuler's planarity theorem, which shows that $\tau / \kappa \rightarrow 0$ along any essential blow-up sequence.


2020 Mathematics subject classification: primary 53E10; secondary 35K59, 37A35.
Keywords and phrases: curve shortening flow, torsion, geometric evolution equation, entropy.

## 1. Introduction

Curve shortening flow is the geometric flow defined by the equation

$$
\begin{equation*}
\partial_{t} \gamma=\kappa N, \tag{1.1}
\end{equation*}
$$

where $\gamma$ is a smooth immersed curve in $\mathbb{R}^{n}, \kappa$ is the curvature and $N$ is the unit normal vector. Solutions to this flow consist of a family of curves $\gamma_{t}$ for $t \in[0, \omega)$ with $\gamma_{0}$ (which we will often denote as $\gamma$ ) as the initial condition.

This flow was introduced by Gage and Hamilton in 1986 as the $L^{2}$ gradient flow for the arc length (that is, the flow which shortens curves the quickest) [5]. Their work established short-time existence and uniqueness for the flow and showed that if one starts with a closed convex curve in the plane, the curve shrinks to a point while becoming asymptotically round. Put succinctly, convex curves shrink to round points. The following year, Grayson [6] proved that any curve which is initially embedded (that is, does not self-intersect) in $\mathbb{R}^{2}$ eventually becomes convex under the flow, and thus converges to a round point.

[^0]In two dimensions, curve shortening flow has two fundamental properties which play a crucial role in its analysis. First, if a curve starts as an embedded curve, it remains embedded and does not self-intersect until it reaches a singularity. More generally, if one considers mean-curvature flow for co-dimension one hypersurfaces, the flow is self-avoiding. In other words, surfaces that do not intersect at the initial time will never intersect in the future. Second, the number of inflection points (that is, points where the curvature changes signs) is nonincreasing under the flow. Both of these facts can be shown by a straightforward application of the parabolic maximum principle but fail for curve shortening flow in higher dimensions.
1.1. Singularity formation. Since curve shortening flow shrinks the length of curves as quickly as possible in the $L^{2}$ topology, a closed curve must encounter a singularity at some time $\omega$. For closed and embedded curves in the plane, the enclosed area decreases linearly at the rate of $-2 \pi$, so it is possible to compute this time explicitly. The singularities are fairly well understood in two dimensions and a natural question is to extend these results to curve shortening flow in dimensions three or higher. To discuss this further, we first introduce some notation.

Curve shortening flow exists so long as the curvature is bounded. So to study singularities, we consider a blow-up sequence, which is a sequence of points in space-time $\left(p_{m}, t_{m}\right)$ such that the curvature at $\left(p_{m}, t_{m}\right)$ goes to infinity. A blow-up sequence is said to be essential if $\kappa^{2}\left(p_{m}, t_{m}\right) \geq \rho M_{t_{m}}$ for some $\rho>0$ where

$$
M_{t}=\sup _{p \in \gamma} \kappa^{2}(p, t) .
$$

One can divide the singularities of curve shortening flow into two broad classes: Type I and Type II. A singularity is said to be Type I if

$$
\limsup _{t \rightarrow \omega} M_{t} \cdot(\omega-t)
$$

is bounded and Type II otherwise. Type-I singularities are global singularities, in that the entire curve shrinks to a point while converging in $C^{\infty}$ to a homothetic (that is, self-similar) shrinking curve. For closed curves in two dimensions, the possible models for these singularities were classified by Abresch and Langer [1]. However, Type-II singularities are local in that the curvature goes to infinity in a small region while possibly remaining bounded elsewhere. Such singularities appear as kinks in the curve. In particular, they admit an essential blow-up sequence which (after rescaling) converges in $C^{\infty}$ to the Grim Reaper curve $y=-\log (\cos x)$, which is a translating soliton under the flow.

As we have mentioned, curve shortening flow behaves differently in higher dimensions, which complicates its analysis. However, Altschuler [2] established that under the flow, curves in three-dimensional space become asymptotically planar near any singularity. More precisely, along any essential blow-up sequence ( $p_{m}, t_{m}$ ), the torsion $\tau$ satisfies

$$
\lim _{m \rightarrow \infty} \frac{\tau}{\kappa}\left(p_{m}, t_{m}\right)=0
$$



Figure 1. An example of a twisted curve.

This result was then extended to curve shortening flow in $\mathbb{R}^{n}$ by Yan and Jiao [11]. As such, the singularity models for curve shortening flow in higher dimensions are the same as for curve shortening flow in the plane, although we cannot rule out the appearance of Abresch-Langer solutions (possibly covered multiple times) or Type-II singularities even when the initial curve is embedded.

## 2. Twisted curves and the curvature-torsion entropy

A curve in $\mathbb{R}^{n}$ is said to be twisted if it has linearly independent derivatives up to order $n$ [4]. In three dimensions, this corresponds to the nowhere vanishing of the curvature and torsion along the curve. As an archetypal example, one can consider a curve which wraps tightly around a torus, as shown in Figure 1.

The main focus of this paper is to study curve shortening flow for twisted curves (that is, curves that are twisted). In particular, we focus on the possible singularities which emerge when a curve is twisted.

THEOREM 2.1. Suppose $\gamma_{t}$ is a solution to curve shortening flow which is twisted up to the time of singularity $\omega$. Then:
(1) the singularity is Type II;
(2) there exists a sequence $\left(p_{m}, t_{m}\right)$ so that $t_{m} \rightarrow \omega$ and

$$
\frac{\tau}{\kappa^{2}}\left(p_{m}, t_{m}\right) \rightarrow \infty
$$

Note that the sequences where $\tau / \kappa^{2} \rightarrow \infty$ cannot be essential, and may not even be a blow-up sequence at all. To establish this fact, we find a quantity that is (nearly) increasing under the flow. In particular, we will study the following entropy functional, whose behaviour is well controlled under the flow.

Definition 2.2. For a twisted curve in $\mathbb{R}^{3}$, the curvature-torsion entropy is defined to be the quantity

$$
\begin{equation*}
\int_{\gamma} \kappa \log \left(\frac{\tau}{\kappa^{2}}\right) d s \tag{2.1}
\end{equation*}
$$

One could extend this definition to nontwisted curves by squaring the argument of the logarithm. However, this integral will essentially always be $-\infty$ whenever there is a flat point (that is, a point with $\tau=0$ ), so we will not consider this generalisation.

## 3. Nearly monotonic functionals

To prove the main result, we must show that the curvature-torsion entropy is nearly nondecreasing under the flow. Before doing so, we start with a simpler proof that a twisted curve cannot develop a Type-I singularity. This result was previously shown in unpublished work of the author [7]. Since the proof is very short, we include it here.

THEOREM 3.1. Suppose $\gamma$ is a twisted curve in $\mathbb{R}^{3}$. Under curve shortening flow, one of the following two possibilities occurs.
(1) There exists a time $t_{0}$ where $\gamma_{t_{0}}$ has a point with vanishing curvature. Furthermore, after this time, $\gamma_{t}$ has a flat point until the singular time.
(2) $\gamma_{t}$ develops a Type-II singularity.

Proof. Consider any curve $\gamma$ (not necessarily twisted) which develops a Type-I singularity at time $\omega$. After rescaling, $\gamma_{t}$ approaches an Abresch-Langer solution [1] with finite winding number in the $C^{\infty}$ sense [2]. This has two consequences.
(a) All blow-up sequences are essential. In other words, for times close to the singularity, the maximum curvature is a bounded multiple of the minimum curvature. As a result, there exists a time $t_{0} \in[0, \omega)$ such that for all times afterward, $\gamma_{t}$ has no inflection points, which implies that torsion is defined everywhere on the curve.
(b) Since $\gamma$ converges to some Abresch-Langer curve, the functional $D(t)=\sup \kappa_{t} \cdot L_{t}$ converges to a finite limit as the time goes to $\omega$, where $L_{t}$ is the length of the curve. In particular, this quantity remains bounded.

Now we consider a solution $\gamma_{t}$ which is twisted after $t_{0}$. For the following calculations, we parametrise $\gamma_{t}$ smoothly by $u \in[0,2 \pi)$ and suppose that the curvature has velocity $v$. To establish the result, we show that for a twisted curve, the total torsion is increasing:

$$
\int_{\gamma_{t}} \tau d s=\int_{0}^{2 \pi} \tau \cdot v d u
$$

To compute the evolution of this quantity, we use the evolution equations for $v, \kappa$ and $\tau$ (derived in $[2,3]$ ):

$$
\begin{align*}
& \partial_{t} v=-\kappa^{2} v \\
& \partial_{t} \kappa=\partial_{s}^{2} \kappa+\kappa^{3}-\kappa \tau^{2}  \tag{3.1}\\
& \partial_{t} \tau=2 \kappa^{2} \tau+\partial_{s}\left(\frac{2 \tau}{\kappa} \partial_{s} \kappa\right)+\partial_{s}^{2} \tau .
\end{align*}
$$

Using these, we find

$$
\begin{aligned}
\partial_{t} \int_{\gamma_{t}} \tau \cdot v d u & =\int_{0}^{2 \pi}\left(\partial_{t} \tau\right) \cdot v+\left(\partial_{t} v\right) \cdot \tau d u \\
& =\int_{0}^{2 \pi}\left(2 \kappa^{2} \tau+\partial_{s}\left(\frac{2 \tau}{\kappa} \partial_{s} \kappa\right)+\partial_{s}^{2} \tau\right) v-\kappa^{2} v \tau d u \\
& =\int_{\gamma_{t}} \kappa^{2} \tau d s+\int_{\gamma} \partial_{s}\left(\frac{2 \tau}{\kappa} \partial_{s} \kappa\right)+\partial_{s}^{2} \tau d s \\
& =\int_{\gamma_{t}} \kappa^{2} \tau d s .
\end{aligned}
$$

Therefore, the $L^{1}$ norm of $\tau$ is increasing and approaches a positive (possibly infinite) limit as $t$ goes to $\omega$. However,

$$
\sup _{p \in \gamma_{t}} \tau(p) \cdot L_{t} \geq\|\tau\|_{1}(t)>0
$$

When combined with the fact that $D(t)$ remains bounded, this implies that

$$
\lim _{t \rightarrow \omega} \sup _{p \in \gamma_{t}} \frac{\tau}{\kappa}>0
$$

which contradicts the planarity theorem. As a result, the curve must develop a Type-II singularity. To complete the proof, we show that if a curve is twisted, it cannot become untwisted unless a point of zero curvature appears.

Proposition 3.2. Suppose we have a family of curves $\gamma_{t}$ in $\mathbb{R}^{3}$ which satisfy (1.1) and that $\gamma_{0}$ is twisted. Furthermore, suppose that $\gamma_{t}$ has no inflection points for $t \in\left[0, t_{0}\right]$. Then for all $t \in\left[0, t_{0}\right], \gamma_{t}$ is also twisted.

This proposition follows from the maximum principle. Suppose that we have a point ( $p, t$ ) so that $\tau(p, t)=0$ and this is the first time when $\tau$ is ever nonpositive. Since both $\tau$ and $\partial_{s} \tau$ are zero,

$$
\partial_{t} \tau(p)=\partial_{s}^{2} \tau+2\left(\partial_{s} \log \kappa\right)\left(\partial_{s} \tau\right)+2 \tau\left(\partial_{s}^{2} \log \kappa+\kappa^{2}\right)=\partial_{s}^{2} \tau \geq 0
$$

By the strong parabolic maximum principle, $\tau$ must remain strictly positive.
This argument fails at inflection points, where torsion is not defined. As such, this result shows that for a Type-I singularity to develop from a twisted curve, an inflection point must emerge and, afterward, a flat point is created where the inflection point occurred. It might seem curious that a single flat point will emerge as we initially expect the torsion to switch signs twice. However, the Frenet-Serret frame bundle can become nontrivial after the emergence of an inflection point.
3.1. The main result. We now turn our attention to proving the main result. To begin, we compute several more time derivatives:

$$
\begin{align*}
\partial_{t} \int_{\gamma_{t}} \kappa d s= & -\int_{\gamma_{t}} \kappa \tau^{2} d s \\
\partial_{t} \int_{\gamma_{t}} \kappa \log \kappa d s= & \int_{\gamma_{t}}(\log \kappa+1)\left(\partial_{s}^{2} \kappa+\kappa^{3}-\kappa \tau^{2}\right)-\kappa^{3} \log \kappa d s \\
= & \int_{\gamma_{t}}-\frac{\left(\partial_{s} \kappa\right)^{2}}{\kappa}-(\kappa \log \kappa) \tau^{2}+\kappa^{3}-\kappa \tau^{2} d s  \tag{3.2}\\
\partial_{t} \int_{\gamma_{t}} \kappa \log \tau d s= & \int_{\gamma_{t}}\left(\partial_{s}^{2} \kappa+\kappa^{3}-\kappa \tau^{2}\right) \log \tau \\
& +\frac{\kappa}{\tau}\left(2 \kappa^{2} \tau+\partial_{s}\left(2 \tau \partial_{s} \log \kappa\right)+\partial_{s}^{2} \tau\right)-\kappa^{3} \log \tau d s \\
= & \int_{\gamma_{t}}-\kappa \tau^{2} \log \tau+2 \kappa^{3}-2 \frac{\left(\partial_{s} \kappa\right)^{2}}{\kappa}+\kappa\left(\partial_{s} \log \tau\right)^{2} d s . \tag{3.3}
\end{align*}
$$

Combining (3.2) and (3.3), we find the following evolution equation for the curvature-torsion entropy:

$$
\begin{equation*}
\partial_{t} \int_{\gamma_{t}} \kappa \log \left(\frac{\tau}{\kappa^{2}}\right) d s=\int_{\gamma_{t}}-\kappa \tau^{2} \log \left(\frac{\tau}{\kappa^{2}}\right)+\kappa\left(\partial_{s} \log \tau\right)^{2}+2 \kappa \tau^{2} d s \tag{3.4}
\end{equation*}
$$

This immediately provides a second proof that twisted curves cannot develop Type-I singularities. In particular, for a Type-I singularity, $\tau / \kappa^{2}$ goes to zero uniformly (by Altschuler's planarity theorem and the fact that all sequences to the singular time are essential). As such, the curvature-torsion entropy must go to negative infinity for a Type-I singularity. However, once $\sup \log \left(\tau / \kappa^{2}\right)<2$, the curvature-torsion entropy is increasing.

Furthermore, we can also show that $\log \left(\tau / \kappa^{2}\right)$ blows up along some sequence. Suppose that there is a uniform bound

$$
\log \left(\frac{\tau}{\kappa^{2}}\right)<C_{1}
$$

Then (2.1) must go to negative infinity as $t$ goes to $\omega$. To see this, consider the region $S \subset \gamma_{t}$ where $\log \left(\tau / \kappa^{2}\right)>0$. On this set,

$$
\int_{S} \kappa \log \left(\frac{\tau}{\kappa^{2}}\right) d s \leq C_{1} \int_{S} \kappa d s \leq C_{1} \int_{\gamma_{0}} \kappa d s
$$

(since the total curvature is decreasing). As such, the positive part of the integral is bounded from above. However, $\gamma_{t}$ has a region that converges to a Grim Reaper curve, whose curvature-torsion entropy is $-\infty$.

To reach a contradiction, we can estimate the left-hand side of (3.4) by

$$
\partial_{t} \int_{\gamma_{t}} \kappa \log \left(\frac{\tau}{\kappa^{2}}\right) d s \geq \int_{\gamma_{t}}-\left(C_{1}-2\right) \kappa \tau^{2} d s=\left(C_{1}-2\right) \partial_{t} \int_{\gamma_{t}} \kappa d s
$$

Since the total curvature decreases to a positive limit as $t$ goes to $\omega$, this shows that the difference between the curvature-torsion entropy at the present time and the singular time is bounded from below, and so cannot go to negative infinity.
3.2. Points with large torsion and curvature. Theorem 2.1 shows that the potential singularities of a twisted curve are highly unusual and we suspect they cannot occur. One strategy would be to try to find an essential sequence so that $\tau / \kappa$ does not go to zero. Although we cannot show this (or even that $\log \left(\tau / \kappa^{2}\right)$ goes to infinity along a blow-up sequence), we can show a weaker result in this direction.

Proposition 3.3. Suppose $\gamma$ is a curve in $\mathbb{R}^{3}$ which develops a twisted singularity. Then one of the following two possibilities occurs.
(1) There exists a sequence $\left(p_{n}, t_{n}\right)$ so that $\kappa\left(p_{n}, t_{n}\right) \rightarrow 0$.
(2) There is a sequence $\left(p_{n}, t_{n}\right)$ so that both

$$
\tau \text { and }\left(2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa\right)\left(\omega-t_{n}\right)^{\alpha}
$$

tend to infinity for $\alpha<1$. Furthermore, this sequence consists of the points whose torsion is maximised on $\gamma_{t_{n}}$.

Proof. If we assume that $\kappa$ is bounded away from zero near the singular time, then Theorem 2.1 shows that $\log (\tau)$ must go to infinity, and thus we must show that we can extract a sequence so that $\left(2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa\right)(\omega-t)^{\alpha}$ blows up. We calculate

$$
\begin{aligned}
\partial_{t} \log (\tau) & =\frac{1}{\tau}\left(2 \kappa^{2} \tau+\partial_{s}\left(\frac{2 \tau}{\kappa} \partial_{s} \kappa\right)+\partial_{s}^{2} \tau\right) \\
& =2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa+2\left(\partial_{s} \log \tau\right)\left(\partial_{s} \log \kappa\right)+\frac{\partial_{s}^{2} \tau}{\tau}
\end{aligned}
$$

At the maximum of $\log (\tau)$, the maximum principle implies that

$$
\partial_{s} \log \tau=0 \quad \text { and } \quad \frac{\partial_{s}^{2} \tau}{\tau} \leq 0
$$

At the maximum of $\log (\tau)$, we find that

$$
\partial_{t} \log (\tau) \leq 2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa .
$$

However, for $\sup \log (\tau)$ to go to infinity in finite time, Hamilton's maximum principle shows we must be able to extract a subsequence where

$$
2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa
$$

goes to infinity.
To show the stronger estimate $\left(2 \kappa^{2}+2 \partial_{s}^{2} \log \kappa\left(p_{n}, t_{n}\right)\right)(\omega-t)^{\alpha} \rightarrow \infty$, we suppose that this is not the case. Then, we divide up the time interval $(t, \omega)$ into sub-intervals ( $t_{i},\left(\omega+t_{i}\right) / 2$ ) and apply the maximum principle on each sub-interval. Doing so, we obtain the estimate

$$
\sup _{t \leq t_{n}} \log \tau(p, t)-\sup \log \tau\left(p, t_{0}\right) \leq \sum_{i=0}^{n} \frac{C_{2}}{2^{i(1-\alpha)}}
$$

This estimate is uniformly bounded in $n$, giving a contradiction.
A similar argument shows that we can extract sequences so that both $\kappa^{\rho} \tau$ and $\left((2+\rho) \kappa^{2}+2 \partial_{s}^{2} \log \kappa\right)(t-\omega)^{\alpha}$ go to infinity for any $\rho \in(0,1]$. However, we cannot conclude that $\tau$ must go to infinity on such a sequence, so we do not have a geometric application for this fact.
3.3. A related quantity. As can be seen from Theorems 2.1 and 3.1 , it is possible to control the behaviour of curve shortening flow by finding quantities that are monotone (or nearly monotone) under the flow. There are several other quantities whose evolution is quite simple, and it might be possible to use them to control the singularities that emerge under the flow. For instance, the quantity $\int_{\gamma_{t}} \tau \log \left(\tau^{2} / \kappa^{4}\right) d s$ evolves as follows:

$$
\partial_{t} \int_{\gamma_{t}} \tau \log \left(\frac{\tau^{2}}{\kappa^{4}}\right) d s=\int_{\gamma_{t}}\left(\kappa^{2} \tau \log \left(\frac{\tau^{2}}{\kappa^{4}}\right)+\tau\left(\left(\partial_{s} \log \kappa^{2}\right)^{2}-\frac{1}{2}\left(\partial_{s} \log \tau^{2}\right)^{2}\right)+4 \tau^{3}\right) d s
$$

In this expression, the terms in the argument of the logarithm have been squared so that this quantity is well defined for arbitrary space curves without assuming they are twisted. We do not know of a direct geometric application for this quantity. However, the fact that the evolution is so simple suggests that it may be useful for controlling the formation of singularities.

## 4. A heuristic for the emergence of flat points

It remains an open question to determine the limiting behaviour for generic initial data for spatial curve shortening flow. However, it is reasonable to expect that generic curves converge to round points, the same as for embedded curves in the plane. There are several cases where spatial curve shortening flow is known to converge to a round point. For instance, if the curve is embedded on a standard sphere, we have the following result (a proof can be found in [10]).
THEOREM 4.1. Given a curve $\gamma_{0}$ embedded on a standard sphere $S^{2}$ in $\mathbb{R}^{3}$, under curve shortening flow, $\gamma_{t}$ remains embedded on a shrinking sphere and converges to a round point.

Note that the total torsion of a spherical curve is zero, which immediately implies that any such curve has flat points. In fact, Sedykh's theorem shows there are at least four such points [9]. Furthermore, in recent work, Litzinger showed that curves whose entropy is at most 2 converge to round points.
THEOREM 4.2 [8]. Suppose that $\gamma$ is a smooth curve whose entropy

$$
\lambda(\gamma)=\sup _{x_{0} \in \mathbb{R}^{n}, t_{0}>0}\left(4 \pi t_{0}\right)^{-1 / 2} \int_{\gamma_{t}} e^{-\left|x-x_{0}\right|^{2} / 4 t_{0}} d \mu
$$

satisfies $\lambda(\gamma) \leq 2$. Then under curve shortening flow, $\gamma_{t}$ converges to a round point.

Apart from these results, there is another reason why we do not expect initially twisted curves to remain twisted; the reaction terms for the curvature and torsion tend to create points of vanishing curvature. To see this, we ignore the spatial derivative terms in (3.1) describing the evolution of $\kappa$ and $\tau$ and simply consider the system of coupled ordinary differential equations (ODEs)

$$
\dot{\kappa}=\kappa^{3}-\kappa \tau^{2}, \quad \dot{\tau}=2 \kappa^{2} \tau
$$

This system reduces to the homogeneous equation

$$
\frac{d \kappa}{d \tau}=\frac{1}{2}\left(\frac{\kappa}{\tau}-\frac{\tau}{\kappa}\right),
$$

whose solutions are circular arcs of the form

$$
\kappa(\tau)=\sqrt{C \tau-\tau^{2}} .
$$

As such, no matter how large $\kappa$ is initially, the reaction ODE tends towards a situation where $\kappa$ vanishes. The full evolution equation for the torsion also includes a complicated term involving its derivatives and those of the curvature, so this analysis does not constitute a complete proof. However, if the initial curve is a helix (a curve of constant curvature and torsion), this calculation shows that the limiting configuration is a straight line, but the limiting value of the torsion is nonzero. The limiting value of the torsion is not the torsion of a straight line, which is undefined. Indeed, the limiting value depends on the initial curvature and torsion of the helix.

## Acknowledgements

The author would like to thank Xuan Hien Nguyen, Mizan Khan and Kori Khan for their helpful comments.

## References

[1] U. Abresch and J. Langer, 'The normalized curve shortening flow and homothetic solutions', J. Differential Geom. 23 (1986), 175-196.
[2] S. J. Altschuler, 'Singularities of the curve shrinking flow for space curves', J. Differential Geom. 34 (1991), 491-514.
[3] S. J. Altschuler and M. A. Grayson, 'Shortening space curves and flow through singularities', J. Differential Geom. 35 (1992), 283-298.
[4] S. I. R. Costa, 'On closed twisted curves', Proc. Amer. Math. Soc. 109(1) (1990), 205-214.
[5] M. Gage and R. S. Hamilton, 'The heat equation shrinking convex plane curves', J. Differential Geom. 23 (1986), 69-96.
[6] M. A. Grayson, 'The heat equation shrinks embedded plane curves to round points', J. Differential Geom. 26 (1987), 285-314.
[7] G. Khan, 'A condition ensuring spatial curves develop type-II singularities under curve shortening flow', Preprint, 2015, arXiv:1209.4072.
[8] F. Litzinger, 'Singularities of low entropy high codimension curve shortening flow', Preprint, 2023, arXiv:2304.02487.
[9] V. D. Sedykh, 'Four vertices of a convex space curve', Bull. Lond. Math. Soc. 26 (1994), 177-180.
[10] H. Siming, 'Distance comparison principle and Grayson type theorem in the three dimensional curve shortening flow', Preprint, 2012, arXiv:1209.5146.
[11] Y. Y. Yang and X. X. Jiao, 'Curve shortening flow in arbitrary dimensional Euclidian space', Acta Math. Sin. (Engl. Ser.) 21 (2005), 715-722.

GABRIEL KHAN, Department of Mathematics, Iowa State University, Ames, IA 50011, USA
e-mail: gkhan@iastate.edu


[^0]:    The author is partially supported by Simons Collaboration Grant 849022 (Kähler-Ricci flow and optimal transport).
    © The Author(s), 2023. Published by Cambridge University Press on behalf of Australian Mathematical Publishing Association Inc. This is an Open Access article, distributed under the terms of the Creative Commons Attribution licence (https://creativecommons.org/licenses/by/4.0/), which permits unrestricted re-use, distribution, and reproduction in any medium, provided the original work is properly cited.

